

Euler scheme for SDEs with distributional drifts

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1 The linear SDE

Setting

Main results

2 The McKean-Vlasov SDE

Setting

Main results

3 Numerical results

About the drifts

Convergence rates

4 Conclusion

The main question

- For an SDE

$$\begin{cases} dX_t = \mu(t, X_t)dt + \sigma(t, X_t)dW_t \\ X_0 = x_0, \end{cases}$$

- We say that a discrete time approximation X^m , where m are the time steps, converges strongly with order $\gamma > 0$ at time T if

$$\mathbb{E}|X_T - X_T^m| \leq cm^{-\gamma}.$$

- Classical result tells us that if μ and σ are Lipschitz continuous and have sub-linear growth we have $\gamma = 1/2$, and if $\mu, \sigma \in \mathbb{R}$, we have $\gamma = \infty$. [26, Kloeden & Platen].
- How far can we take the Euler scheme?

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- Convergence rate of the Euler-Maruyama (EM) scheme for **SDEs** with distributional coefficients.
- Convergence rate of the Euler-Maruyama (EM) scheme for **McKean-Vlasov SDEs** with distributional coefficients.
- Implement said numerical methods and compare the empirical and theoretical rate.

- **Preprint:** C. J., Issoglio, Palczewski. *Convergence rate of numerical scheme for SDEs with a distributional drift in Besov space*. [arXiv:2309.11396](https://arxiv.org/abs/2309.11396) [8]
- **Implementation:** C. J., Issoglio, Palczewski. *Implementation of the Numerical Methods*. doi.org/10.5281/zenodo.8239606 [7]



Preprint



Implementation

¹The work on McKean equations is in the last stages of preparation.

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- 4 Conclusion**

We study the SDE

$$\begin{cases} dX_t = b(t, X_t)dt + dW_t \\ X_0 = x_0, \end{cases}$$

- where the drift $b \in C^{1/2}([0, T]; C^{-\beta}(\mathbb{R}))$ for $0 < \beta < 1/2$,
- and W_t is a one-dimensional Brownian motion and $x_0 \in \mathbb{R}$.

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Literature: Theoretical analysis

- [17, *Flandoli, Issoglio & Russo (2017)*] d -dimension with $b(t, \cdot) \in H_{q, \tilde{q}}^{-s}$, virtual solutions.
- [24, 22, *Issoglio & Russo (2023 & 2024)*] d -dimension with $b(t, \cdot) \in C^{(-\beta)+}$, virtual solutions and martingale problem equivalence.
- Related works include [32, *Veretennikov (1981)*], [2, *Bass & Chen (2001)*], [18, 19, *Flandoli, Russo & Wolf (2003 & 2004)*] [6, *Cannizzaro & Chouk (2018)*] [11, *Chaudru de Raynal & Menozzi (2022)*].

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- Existence of solutions is formulated through **virtual solutions**, i.e.

$$X_t = x + v(0, x) - v(t, X_t) + \lambda \int_0^t v(s, X_s) ds + \int_0^t (v_x(s, X_s) + 1) dW_s,$$

- where v is the solution to

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- We then define an auxiliary process $Y_t = v(t, X_t) + X_t$.
 - Denote $\phi(t, x) = u(t, x) + x$.
- The function ϕ has a space inverse ψ , and we see that $X_t = \psi(\cdot, Y_t)$.
- Prove that ψ is 2-Lipschitz and then we can use

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- Two step approach:
 - Approximate the solution to the SDE X_t with a **regularised SDE** X_t^N .
 - Create a **numerical approximation** $X_t^{N,m}$ of the regularised SDE.
- Convergence rate $r(\beta) = \frac{(\frac{1}{2}-\beta)^2}{2(\frac{1}{2}-\beta)^2+\beta+1}$.
 - $\lim_{\beta \downarrow 0} r(\beta) = \frac{1}{6}$.
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The McKean-Vlasov SDE (MVSDE) which concerns us is

$$\begin{cases} dX_t = F(v(t, X_t))b(t, X_t)dt + dW_t \\ X_0 \sim \mu. \end{cases}$$

- Where F is a non-linear function,
- $v(t, \cdot)$ is the law density of X_t ,
- μ is a probability distribution,
- and b is as in the linear SDE, i.e. $b \in C([0, T]; C^{-\beta}(\mathbb{R}))$ for $0 < \beta < 1/2$.

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- Instead of using propagation of chaos results.
- It is proved by [23, *Issoglio & Russo*] that in this case X_t has a law density which is the weak solution of the Fokker-Planck PDE

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- Provided we can solve this, we can use similar techniques as for the linear case.
- The PDE is one dimensional so we opt to solve it numerically.

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Numerical implementation

- The trick of our implementation is in the choice of b .
- We select the drift to be $b = \partial_x B \in C^{-\beta}$ for some function $B \in C^{1-\beta}$.
- The smoothed drift is $b^N = \rho_{\frac{1}{N}} * b = \rho_{\frac{1}{N}} * \partial_x B = \partial_x \rho_{\frac{1}{N}} * B$.

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- We select the drift to be $b = \partial_x B \in C^{-\beta}$ for some function $B \in C^{1-\beta}$.
- The smoothed drift is $b^N = p_{\frac{1}{N}} * b = p_{\frac{1}{N}} * \partial_x B = \partial_x p_{\frac{1}{N}} * B$.

Numerical implementation

- Our choice of the function B is a path of a fBm B^H where $0 < H < 1$.
- The advantages of using an fBm are twofold:
 - ① Having a function that is rough in a whole interval.
 - ② The regularity properties of fBm allow us to identify the space where the drift lives.
- For the McKean SDE we have to additionally find out ρ^N .
- Since the PDE is one-dimensional we can get away with solving it directly.

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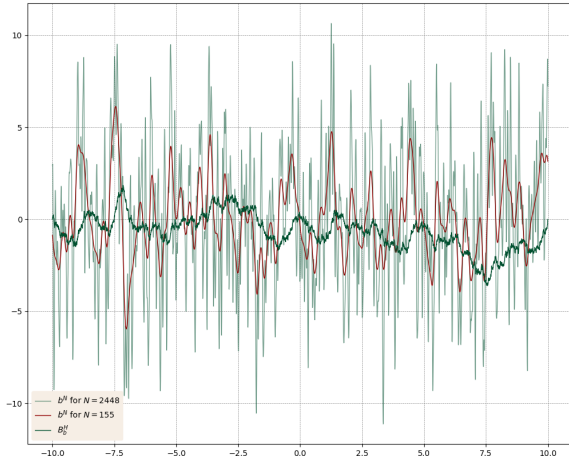
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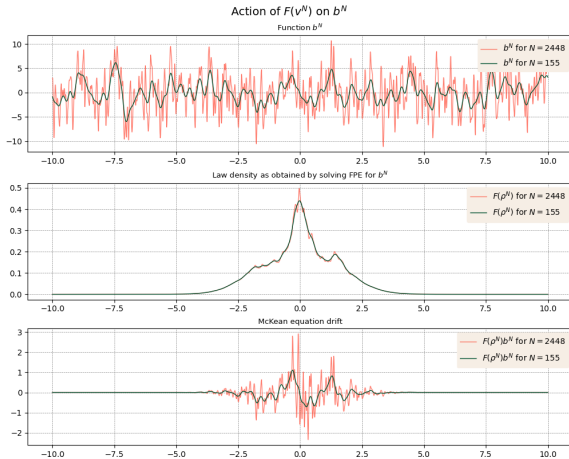
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For the linear SDE



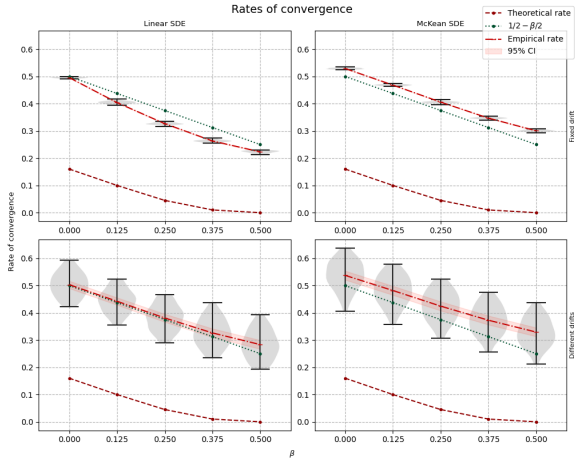
Drift b^N compared to fBm with Hurst coefficient $H = 1/2 - \epsilon$.

For the McKean-Vlasov SDE



Function b^N compared to fBm with Hurst coefficient $H = 1/2 - \epsilon$ and $F(x) = \sin(x)$ displaying the effect of the law of the process.

Theoretical, empirical and hypothetical rates



Comparison of the empirical convergence rate for McKean-Vlasov SDEs with respect to different $\hat{\beta}$ and with hypothesis rate extending [13, [Dareiotis, Gerencsér & Lê](#)].

- 1 The linear SDE
 - Setting
 - Main results
- 2 The McKean-Vlasov SDE
 - Setting
 - Main results
- 3 Numerical results
 - About the drifts
 - Convergence rates
- 4 **Conclusion**

Conclusion and future work

- We get a bound for the convergence rate of SDEs with distributional drifts driven by a standard Brownian motion
- The convergence rate obtained is at least $1/6$ close to the measurable case and 0 for the limit case of the regularity.
- Explore the usage of the stochastic sewing lemma as done by [20] to get the optimal rate of convergence.

Thank you!

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